

1 **Title**

2 Method and System for Identifying and Processing Changes to a Network Topology

3 **Field of Invention**

4 The present invention relates generally to computer networks. More particularly, it relates  
5 to a method and system for identifying changes to a network topology and for acting upon the  
6 network based on the changes.

7 **Background**

8 As communications networks, such as the Internet, carry more and more traffic, efficient  
9 use of the bandwidth available in the network becomes more and more important. Switching  
10 technology was developed in order to reduce congestion and associated competition for the  
11 available bandwidth. Switching technology works by restricting traffic. Instead of broadcasting a  
12 given data packet to all parts of the network, switches are used to control data flow such that the  
13 data packet is sent only along those network segments necessary to deliver it to the target node.  
14 The smaller volume of traffic on any given segment results in few packet collisions on that segment  
15 and, thus, the smoother and faster delivery of data. A choice between alternative paths is usually  
16 possible and is typically made based upon current traffic patterns.

17 The intelligent routing of data packets with resultant reduction in network congestion can  
18 only be effected if the network topology is known. The topology of a network is a description of  
19 the network which includes the location of and interconnections between nodes on the network.  
20 The word "topology" refers to either the physical or logical layout of the network, including devices,  
21 and their connections in relationship to one another. Information necessary to create the topology  
22 layout can be derived from tables stored in network devices such as hubs, bridges, and switches.  
23 The information in these tables is in a constant state of flux as new entries are being added and old  
24 entries time out. Many times there simply is not enough information to determine where to place a  
25 particular device.

26 Switches examine each data packet that they receive, read the source addresses, and log  
27 those addresses into tables along with the switch ports on which the packets were received. If a  
28 packet is received with a target address without an entry in the switches table, the switch receiving it

1 broadcasts that packet to each of its ports. When the switch receives a reply, it will have identified  
2 where the new node lies.

3 In a large network with multiple possible paths from the switch to the target node, this table  
4 can become quite large and may require a significant amount of the switch's resources to develop  
5 and maintain. As an additional complication, the physical layout of devices and their connections  
6 are typically in a state of constant change. Devices are continually being removed from, added to,  
7 and moved to new physical locations on the network. To be effectively managed, the topology of a  
8 network must be accurately and efficiently ascertained, as well as maintained.

9 Existing mapping methods have limitations that prevent them from accurately mapping  
10 topological relationships. Multiple connectivity problems are one sort of difficulty encountered by  
11 existing methods. For example, connectors such as routers, switches, and bridges may be  
12 interconnected devices in a network. Some existing methods assume that these devices have only a  
13 single connection between them. In newer devices, however, it is common for manufacturers to  
14 provide multiple connections between devices to improve network efficiency and to increase  
15 capacity of links between the devices. The multiple connectivity allows the devices to maintain  
16 connection in case one connection fails. Methods that do not consider multiple connectivity do not  
17 present a complete and accurate topological map of the network.

18 Another limitation of existing topology methods is the use of a single reference to identify a  
19 device. Existing methods use a reference interface or a reference address in a set of devices to  
20 orient all other devices in the same area. These methods assumed that every working device would  
21 be able to identify, or "hear," this reference and identify it with a particular port of the device. With  
22 newer devices, however, it is possible that the same address or reference may be heard out of  
23 multiple ports of the same device. It is also possible that the address or reference may not be heard  
24 from any ports, for example, if switching technology is used.

25 Still another limitation of existing mapping systems is that they require a complete copy of  
26 the topological database to be stored in memory. In larger networks, the database is so large that  
27 this really is not feasible, because it requires the computer to be very large and expensive.

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1 Still another difficulty with existing systems is that they focus on the minutia without  
2 considering the larger mapping considerations. Whenever an individual change in the system is  
3 detected, existing methods immediately act on that change, rather than taking a broader view of the  
4 change in the context of other system changes. For example, a device may be removed from the  
5 network temporarily and replaced with its ports reversed. In existing systems, this swapped port  
6 scenario could require hundreds or thousands of changes because the reference addresses will have  
7 changed for all interconnected devices.

8 Still another disadvantage of existing methods is that they use a continuous polling paradigm.  
9 These methods continuously poll network addresses throughout the day and make decisions based  
10 on those continuous polling results. This creates traffic on the network that slows other processes.

11 Still another limitation of existing methods is the assumption that network parts of a  
12 particular layer would be physically separated from other parts. Network layer 1 may represent the  
13 physical cabling of the network, layer 2 may represent the device connectivity, and layer 3 may  
14 represent a higher level of abstraction, such as the groupings of devices into regions. Existing  
15 methods assume that all layer 3 region groupings are self-contained, running on the same unique  
16 physical networking. However, in an internet protocol (IP) network, multiple IP domains may co-  
17 exist on the same lower layer networking infrastructure. It has become common for a network to  
18 employ a virtual local area network (LAN) to improve security or to simplify network maintenance,  
19 for example. Using virtual LANs, a system may have any number of different IP domains sharing  
20 the same physical connectivity. As a result, existing methods create confusion with respect to  
21 topological mapping because networks with multiple IP addresses in different subnets for the  
22 infrastructure devices cannot be properly represented because they assume the physical separation  
23 of connectivity for separate IP domains. Still another limitation of existing methods is that they do  
24 not allow topological loops, such as port aggregation or trunking, and switch meshing.

25  
26 **Summary of Invention**

27 A method and system are disclosed for mapping the topology of a network having  
28 interconnected nodes by identifying changes in the network and updating a stored network topology

1 based on the changes. The nodal connections are represented by data tuples that store information  
2 such as a host identifier, a connector interface, and a port specification for each connection. A  
3 topology database stores an existing topology of a network. A topology converter accesses the  
4 topology database and converts the existing topology into a list of current tuples. A connection  
5 calculator calculates tuples to represent connections in the new topology. The topology converter  
6 receives the new tuples, identifies changes to the topology, and updates the topology database using  
7 the new tuples. The topology converter identifies duplicate tuples that appear in both the new tuples  
8 and the existing tuples and marks the duplicate tuples to reflect that no change has occurred to these  
9 connections. The topology converter attempts to resolve swapped port conditions and searches for  
10 new singly-heard and multi-heard host link tuples in the list of existing tuples. The topology  
11 converter also searches for new conflict link tuples in the existing tuples. The topology converter  
12 updates the topology database with the new topology.

### 13 Summary of Drawings

14 Figure 1 is a drawing of a typical topological bus segment for representing the connectivity  
15 of nodes on a network.

16 Figure 2 is a drawing of a typical topological serial segment for representing the connectivity  
17 of nodes on a network.

18 Figure 3 is a drawing of a typical topological star segment for representing the connectivity  
19 of nodes on a network.

20 Figure 4 is a drawing of another typical topological star segment for representing the  
21 connectivity of nodes on a network.

22 Figure 5 is a drawing of the connectivity of an example network system.

23 Figure 6 is a drawing of the connectivity of another example network system.

24 Figure 7 is a block diagram of the system.

25 Figure 8 is a flow chart of the method of the system.

26 Figure 9 is a flow chart of the method used by the tuple manager.

27 Figure 10 is a flow chart of the method used by the connection calculator.



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1 As used herein, a node is any electronic component, such as a connector or a host, or  
2 combination of electronic components with their interconnections. A connector is any network  
3 device other than a host, including a switching device. A switching device is one type of connector  
4 and refers to any device that controls the flow of messages on a network. Switching devices  
5 include, but are not limited to, any of the following devices: repeaters, hubs, routers, bridges, and  
6 switches.

7 As used herein, the term "tuple" refers to any collection of assorted data. Tuples may be  
8 used to track information about network topology by storing data from network nodes. In one use,  
9 tuples may include a host identifier, interface information, and a port specification for each node.  
10 The port specification (also described as the group/port) may include a group number and a port  
11 number, or just a port number, depending upon the manufacturer's specifications. A binary tuple  
12 may include this information about two nodes as a means of showing the connectivity between them,  
13 whether the nodes are connected directly or indirectly through other nodes. A "conn-to-conn"  
14 tuple refers to a tuple that has connectivity data about connector nodes. A "conn-to-host" tuple  
15 refers to a tuple that has connectivity data about a connector node and a host node. In one use,  
16 tuples may have data about more than two nodes; that is, they may be n-ary tuples, such as those  
17 used with respect to shared media connections described herein.

18 A "singly-heard host" (shh) refers to a host, such as a workstation, PC, terminal, printer,  
19 other device, etc., that is connected directly to a connector, such as a switching device. A singly-  
20 heard host link (shhl) refers to the link, also referred to as a segment, between a connector and an  
21 shh. A "multi-heard host" (mhh) refers to hosts that are heard by a connector on the same port that  
22 other hosts are heard. A multi-heard host link (mhhl) refers to the link between the connector and  
23 an mhh. A link generally refers to the connection between nodes. A segment is a link that may  
24 include a shared media connection.

25 Figure 1 is a drawing of a typical topological bus segment 100 for representing the  
26 connectivity of nodes on a network 110. In Figure 1, first and second hosts 121, 122, as well as a  
27 first port 131 of a first connector 140 are interconnected via the network 110. The bus segment

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1 100 comprises the first and second hosts 121, 122 connected to the first port 131 of the first  
2 connector 140.

3 Figure 2 is a drawing of a typical topological serial segment 200 for representing the  
4 connectivity of nodes on the network 110. In Figure 2, the first host 121 comprises a second port  
5 132 on a second connector 145 which is connected via the network 110 to the first port 131 on the  
6 first connector 140. The serial segment 200 comprises the second port 132 on the second  
7 connector 145 connected to the first port 131 on the first connector 140. Figure 2 is an example of  
8 a connector-to-connector ("conn-to-conn") relationship.

9 Figure 3 is a drawing of a typical topological star segment 301 for representing the  
10 connectivity of nodes on the network 110. In Figure 3, the first host 121 is connected to the first  
11 port 131 of the first connector 140. The star segment 301 comprises the first host 121 connected  
12 to the first port 131 of the first connector 140. Figure 3 is an example of a connector-to-host  
13 ("conn-to-host") relationship.

14 Figure 4 is a drawing of another typical topological star segment 301 for representing the  
15 connectivity of nodes on the network 110. In addition to the connections described with respect to  
16 Figure 3, a third host 123 is connected to a third port 133 of the first connector 140 and a fourth  
17 host 124 is connected to a fourth port 134 of the first connector 140. In Figure 4, the star segment  
18 301 comprises the first host 121 connected to the first port 131 of the first connector 140, the third  
19 host 123 connected to the third port 133 of the first connector 140, and the fourth host 124  
20 connected to the fourth port 134 of the first connector 140. Thus, the star segment 301 comprises,  
21 on a given connector, at least one port, wherein one and only one host is connected to that port,  
22 and that host. In the more general case, the star segment 301 comprises, on a given connector, all  
23 ports having one and only one host connected to each port, and those connected hosts. Since the  
24 segments, or links, drawn using the topological methods of Figure 4 resemble a star, they are  
25 referred to as star segments.

26 For illustrative purposes, nodes in the figures described above and in subsequent figures are  
27 shown as individual electronic devices or ports on connectors. Also, in the figures the nodes are

1 represented as terminals. However, they could also be workstations, personal computers, printers,  
2 scanners, or any other electronic device that can be connected to networks 110.

3 Figure 5 is a drawing of the connectivity of an example network system. In Figure 5, first,  
4 third, and fourth hosts 121, 123, 124 are connected via the network 110 to first, third, and fourth  
5 ports 131, 133, 134 respectively, wherein the first, third, and fourth ports 131, 133, 134 are  
6 located on the first connector 140.

7 The first, third and fourth hosts 121, 123, 124 are singly-heard hosts connected to separate  
8 ports 131, 133, 134 of a common connector 140 – the first connector 140. The fifth and sixth  
9 hosts 125, 126 are singly-heard hosts connected to the third and fourth connectors 142, 143. The  
10 seventh and eighth hosts 127, 128 are multi-heard hosts connected to the same port 139 of the fifth  
11 connector 144. The multi-heard hosts 127, 128 illustrate a shared media segment 180, also  
12 referred to as a bus 180.

13 The second, third, fourth, and fifth connectors 141, 142, 143, 144 are interconnected and  
14 illustrate a switch mesh 181. Each of the connectors in the switch mesh 181 is connected to each  
15 other, either directly or indirectly, to create a fully meshed connection. In the mesh, traffic may be  
16 dynamically routed to create an efficient flow.

17 Figure 5 also shows an example of a port aggregation 182, also referred to as trunking 182.  
18 The first connector 140 is connected via the network 110 to the second connector 141 by two  
19 direct links, each of which is connected to different ports on the connectors. One link is connected  
20 to the sixth port 136 of the first connector 140 and to the seventh port of the second connector  
21 137. The other link is connected to fifth port 135 of the first connector 140 and to the eighth port  
22 138 of the second connector 141. In this example, two connectors illustrate the multiple  
23 connectivity between nodes. Depending upon the device specifications, devices such as connectors  
24 may be connected via any number of connectors. As explained herein, the system resolves multiple  
25 connectivity problems by tracking port information for each connection.

26 Figure 6 is a drawing of the connectivity of a portion of a network having three connectors  
27 171, 172, 173. A first host 151 is connected directly to the first port 161 of the first connector 171  
28 and the second host 152 is connected to a sixth port 166 of the third connector 173. The second





1 information is assembled into a tuple and may be used as a "hint" to determine its connectivity later,  
 2 based on other connections. The tuple manager 300 may also gather 920 additional information  
 3 about the network or about particular nodes as needed. For example, the connection calculator  
 4 320 may require additional node information and may signal the tuple manager 300 to gather that  
 5 information.

6 After the data is gathered and the tuples are stored in the neighbor database 310, the  
 7 connection calculator 320 processes the tuples to reduce them to relationships in the topology.  
 8 Figure 10 shows a flow chart of the process of the connection calculator 320, as shown generally in  
 9 the reduction step 906 of the method shown in Figure 8. The connection calculator 320 performs a  
 10 first weeding phase 922 to identify singly-heard hosts to distinguish them from multi-heard hosts.  
 11 Singly-heard hosts refer to host devices connected directly to a connector. The connection  
 12 calculator 320 then performs an infrastructure-building phase 924 to remove redundant connector-  
 13 to-connector links and to complete the details for partial tuples that are missing information. Then,  
 14 the connection calculator 320 performs a second weeding phase 926 to resolve conflicting reports  
 15 of singly-heard hosts. The connection calculator 320 then performs a noise reduction phase 928 to  
 16 remove redundant neighbor information for connector-to-host links. If clarification of device  
 17 connectivity is required, the connection calculator 320 performs a "look for" phase 930 to ask the  
 18 tuple manager 300 to gather additional data. The tuple data is then consolidated 932 into segment  
 19 and network containment relationships. The connection calculator 320 may also tag redundant  
 20 tuples to indicate their relevance to actual connectivity. These redundant tuples may still provide  
 21 hints to connectivity of other tuples. As part of the consolidation phase 932, the connection  
 22 calculator 320 creates new n-ary tuples (tuples having references to three or more tucos) for shared  
 23 media segments.

24 Figure 11 is a flow chart of the connection calculator's first weeding process 922 for  
 25 distinguishing singly-heard hosts. The purpose of the first weeding process 922 is to identify the  
 26 direct connections between connectors and hosts; that is, those tuples having a first tuco that is a  
 27 connector and a second tuco that is a host. The connection calculator 320 looks through the tuple  
 28 list in the neighbor database 310, and for each tuple 402, the connection calculator 320 determines



1 manufactures tuples based on the list of singly-heard host link tuples identified in the first weeding  
 2 phase 922. The purpose is to identify the relationship between the connectors in the extra host links  
 3 tuples and the connectors directly connected to the singly-heard hosts. For each singly-heard host  
 4 link 420, the connection calculator 320 processes 422 each extra host link that refers to the host.  
 5 In the illustration of Figure 6, a conn-to-conn link tuple would represent the connection between the  
 6 first connector 171 and the intermediate connector 172. An extra host link tuple would represent  
 7 the indirect connection between the intermediate connector 172 and the first host 151. The conn-  
 8 to-conn link tuple between the first connector 171 and the intermediate connector 172 is an  
 9 example of an ehConn-to-shhlConn tuple. If a conn-to-conn link tuple exists 424 for the extra host  
 10 link connector to the singly-heard host link connector (ehConn-to-shhlConn), then the connection  
 11 calculator 320 updates 428 the tuple if it is incomplete. It is possible that the tuple data may be  
 12 incomplete and a conn-to-conn link may not exist. In that case, a conn-to-conn tuple does not exist  
 13 for the ehConn-to-shhlConn, then such a tuple is created 426.

14 After processing extra host links for singly-heard host links, the connection calculator 320  
 15 considers 430 each connector (referred to as conn1) in the tuples to determine the relationship  
 16 between connectors. As illustrated in Figure 6, a single connector may be connected directly and  
 17 indirectly to multiple other connectors. In Figure 6, the first connector 151 is connected to the  
 18 intermediate connector 171 directly and also to the third connector 173 indirectly. The third  
 19 connector 173 hears the first host 151 on the same part 165 that it hears the first connector 171 and  
 20 the intermediate connector 172. The infrastructure building phase 924 tries to determine the  
 21 relationship between other connectors heard on the same port of conn1. In a series of  
 22 interconnected connectors, the connector on one end may not hear a connector on another end, but  
 23 it may hear intermediate connectors, that in turn hear their own intermediate connectors. Tuples are  
 24 created to represent the interconnection of conn-to-conn relationships. Based on this data, the  
 25 connection calculator 320 can make inferences regarding the overall connection between  
 26 connectors.

27 For every conn1, the connection calculator 320 considers 432 every other connector  
 28 (conn2) to determine whether a conn1-to-conn2 tuple exists. If conn1-to-conn2 does not exist,

1 then the connection calculator 320 considers 436 every other conn-to-conn tuple containing conn2.  
 2 The other connector on this tuple may be referred to as conn3. If conn2 hears conn3 on a unique  
 3 port 438 and if conn1 also hears conn3 440, then the connection calculator 320 creates 442 a tuple  
 4 for conn1-to-conn2 in the connector-to-connector links tuple list.

5 After processing all of the conn1 tuples, the connection calculator 320 processes 444 each  
 6 conn1-to-conn2 links tuple to ensure that they have complete port data. For each incomplete tuple  
 7 446, the connection calculator 320 looks 448 for a different tuple involving conn1 in the extra host  
 8 links tuples on a different port. If a different tuple is found 450, then the connection calculator 320  
 9 determines 452 whether conn2 also hears the host. If conn2 does hear the host, then the  
 10 connection calculator 320 completes the missing port data for conn2. If conn2 does not also hear  
 11 the host 452, then the connection calculator 320 continues looking 448 through different tuples  
 12 involving conn1 in extra host links on different ports.

13 After attempting to complete the missing data in each of the conn-to-conn links tuples, the  
 14 connection calculator 320 processes 456 each conn-to-conn links tuple. The purpose of this sub-  
 15 phase is to attempt to disprove invalid conn-to-conn links. The connection calculator 320 considers  
 16 458 conn1 and conn2 of each conn-to-conn links tuple. Every other connector in conn-to-conn  
 17 links may be referred to as testconn. For each testconn 460, the connection calculator 320  
 18 determines 462 whether the testconn hears conn1 and conn2 on different groups/ports. If testconn  
 19 hears conn1 and conn2 on different ports, then the tuple is moved to extraconnlinks (ecl) 464.

20 Otherwise, the connection calculator 320 continues processing 460 the remaining testconns.

21 Figure 13 shows a flow chart of the second weeding phase 926. The purpose of the  
 22 second weeding phase 926 is to attempt to resolve conflicts involving singly-heard hosts identified in  
 23 the first weeding phase 922. In the situation described herein in which more than one connector  
 24 reports that a host is singly-heard, the second weeding phase 926 reviews the tuples created during  
 25 the infrastructure-building phase 924 involving the connector and host in question and attempts to  
 26 disprove the reported conflict. The connection calculator 320 processes 466 each  
 27 singleConflictLinks (scl) tuple (sometimes referred to as the search tuple) and considers 468 conn1  
 28 and host1 of the tuple. For each extra host links tuple containing host1 470, the connection

1 calculator 320 considers 472 conn2 of the tuple. If there is a tuple in conn-to-conn links for conn2  
 2 and conn1 474, and if there is a conn2-to-conn1 tuple in the extra host links tuples 476, and if the  
 3 port is the same for conn2 hearing conn1 and host1 478, then the search tuple is moved 480 into  
 4 the singly heard host links and other tuples containing host1 are removed 482 from the  
 5 singleConflictLinks.

6 Figure 14 shows a flow chart of the noise reduction phase 928. The purpose of the noise  
 7 reduction phase 928 is to handle those connections in which a connector is not directly connected  
 8 to a host or to another connector. For example, networking technology may employ shared media  
 9 connections between connectors, rather than dedicated media connectors. With a shared media  
 10 connection, the entries in the forwarding tables for connectors attached to the shared media  
 11 connection will include every node accessing the shared media connection and may not present a  
 12 useful or accurate representation of the nodal connection. For example, if the network configuration  
 13 in Figure 6 used a shared media connection between the first connector 171 and the intermediate  
 14 connector 172, then the first connector is not really connected directly to the intermediate connector  
 15 because other devices (not shown in Figure 6) may also use the shared media connection. These  
 16 other devices may include web servers, other connectors, other subnetworks, etc. Tuples will be  
 17 created for the connectors 171, 172 on opposing ends of the shared media. In this situation, it is  
 18 inefficient to maintain point-to-point binary tuples for every connection. The noise reduction phase  
 19 928 disproves invalid tuples created by the shared media connections.

20 For each multi-heard host links (mhhl) tuple, also referred to as multiHeardLinks (mhl)  
 21 tuples (sometimes referred to as the search tuple) 484, conn1 and host1 are considered 486. For  
 22 each extra host links tuple containing host1 488, conn2 is considered 490. If there is a tuple in  
 23 conn-to-conn links for conn2 and conn1 492, and if there is a conn2-to-host1 tuple in  
 24 extraHostLinks 494, and if the group/port for conn2 hearing conn1 and host1 is different 496, then  
 25 the search tuple is moved 498 to extraHostLinks.

26 Figure 15 shows a flow chart for the "look for" phase 930. The purpose of this phase is to  
 27 complete missing data for mhhl tuples. There may exist connections on the network that have  
 28 incomplete tuple data. For example, the network may simply have no traffic between certain nodes,

in which case data might not be stored in forwarding tables. In another example, a forwarding table may not have sufficient room to store all of the required information and might delete data on a FIFO basis. In the look for phase 930, the connection calculator 320 instructs the tuple manager 300 to query specific nodes to retrieve the missing data. Data that was not stored in a forwarding table on the first interrogation may be present on a subsequent query. For each mhh1 tuple 500, the connection calculator 320 considers 502 conn1 and host1. If the conn1 group/port is already in an “alreadyDidLookfors” list, then a list is created 508 for all connectors in conn-to-conn links that are heard by conn1 on the same group/port as host1. For each connector (conn2) in the list 510, the connection calculator 320 determines 512 whether there is a conn2-to-host1 tuple in the mhh1 tuples. If there is not such a tuple, then the connection calculator 320 initiates a look-for for conn2-to-host1 via the tuple manager 300. When each connector in the list has been processed 510, the conn1 group/port tuco is added 516 to an alreadyDidLookfors list. As an additional portion of the look for phase 930 (not shown in figures) the system may ask a user to verify or clarify information about connectivity. For example, the system may show the user the perceived connectivity or the unresolved connectivity issues and request the user to add information as appropriate.

16 The connection calculator 330 process described above collects the tuple information from  
17 the tuple manager 300, builds tuples new tuples and removes redundant or unnecessary tuples to  
18 produce the new topology. This topology may have incomplete tuples possibly resulting from  
19 extraneous information that the connection calculator 330 could not disprove. To refine the new  
20 topology, the connection calculator 330 can request the tuple manager 300 to obtain additional  
21 information about particular nodes or it may also request a user to refine the topology by adding or  
22 removing tuples. Using the process of the connection calculator 330, tuples marked as non-  
23 essential may be removed from the new topology to save space and to simplify the topology. The  
24 connection calculator 330 is not confused by multiple connectivity situations such as port  
25 aggregation 182 or switch meshing 181 as shown in Figure 5, because the tuples represent point-  
26 to-point, or neighbor-to-neighbor, connectivity showing each connection in the network. This  
27 point-to-point connectivity concept also helps enable the system to avoid difficulties that occur in





1 the topology converter 340 determines 556 whether the conniface is connected to a star segment.  
 2 If it is connected to a star segment, then for every other interface in the segment 558, the topology  
 3 converter 340 determines 560 whether there is an existing shs tuple, referred to as the "topo tuple"  
 4 for the segment. If there is no such tuple, then the topology converter 340 creates 562 a topo shs  
 5 tuple. The tuco for the interface's host-to-topo shs is then added 564 to the topo shs tuple.

6 If the connector node is not connected to a star segment 556 and is connected to a bus  
 7 segment 566, the topology converter 340 determines 568 whether there is an existing mhs tuple for  
 8 conn1. If there is not an existing mhs tuple for conn1, then a topo mhs tuple is created 570. A tuco  
 9 is added 572 for the host to the mhs tuple.

10 If the connector node is not connected to either a star segment 556 or to a bus segment  
 11 566, then the topology converter knows that it is connected to another connector (conn2). If such  
 12 a connector does not already have an existing connLinks tuple for conn1 and conn2 576, then a  
 13 connLinks tuple is created 578. After processing the bus segment, star segment, and conn-to-conn  
 14 segment, for each conniface 554, the topology converter 340 proceeds to the next node 550.

15 Figure 18b shows a continuation of the flow chart of Figure 18a showing the steps of the  
 16 method when the topology converter 340 determines that the node is not a connector 552. If the  
 17 node is in the default segment, then an "unheardOfLinks" tuple is created 582 and the topology  
 18 converter proceeds to the next node 550. If the node is not in the default segment 580, then the  
 19 topology converter 340 determines whether the node is in a star segment 584. If the node is in a  
 20 star segment, then if there is not already an shs tuple, the topology converter 340 creates 588 an shs  
 21 tuple. The tuco for the node is then added 590 to the shs tuple, and the topology converter 340  
 22 proceeds to the next node 550.

23 If the node is not in a star segment, then the topology converter 340 knows that it is in the  
 24 bus segment. If there is not already an mhs tuple for the node, 594, then the topology converter  
 25 340 creates 596 an mhs tuple. The tuco for the node is then added 598 to the mhs tuple, and the  
 26 topology converter proceeds to the next node 550.

27 Figure 19 shows a flow chart for the discard duplicates phase 936 of the topology  
 28 converter 340. For each tuple in the new tuples (nt) 600, the topology converter looks for 602 an

exact match in the current tuples stored in the topodb. If an exact match is found 604, then the new tuple is marked 606 as "no change" indicating that this is an identical tuple.

Figures 20a-d show a flow chart for the identify different tuples phase 938. The system looks through each tuple in the new SinglyHeardSegments (newSHS) tuple list 608 and tries to identify and fix 610 swapped ports on connectors. Swapped ports are identified by considering those segment tuples in both the new topology and the existing topology that differ only by the port specification in the tuco. Each tuple that is fixed as a swapped port is marked 612 as "handled." The system also looks through each tuple in the new multiHeardSegments tuple list (newMHS) 614 and tries to identify and fix 616 swapped ports on connectors. Each tuple that is fixed as a swapped port is marked 618 as "handled."

The system then processes 620 each unmarked tuple in the newSHL tuples. Four cases are possible for the host of the newSHL tuples. The host of the newSHL can be found in the current singlyHeardLinks (curSHL) 622, the current multiHeardLinks (curMHL) 630, the current connLinks (curCL) 638, or the current UnheardOfLinks (curUOL) 642. If the host of a newSHL tuple is found 622 in the current SinglyHeardLinks (curSHL) tuples, then the system determines 624 if there is a matching connector tuco between the newSHL tuples and the curSHL tuples. If there is a matching tuco, then the system changes 626 the host connection attribute. If there is not a matching tuco, then the host connection is moved 628 in the topology.

If the host is found in the curMHL tuples 630, then the system determines 632 whether there is a matching connector tuco between the newSHL tuples and the curSHL tuples. If there is a matching connector, then the segment type of connection is changed 634. If there is not a matching connector, then the host connection is moved 636 in the topology. If the host is found in the curCL tuples 638, then the host is moved 640 into a star segment of the connector. If it is found in the curUOL 642, then the host is moved 644 into the star segment of the connector.

Figure 20c shows another stage of the processing undertaken during the identify different tuples phase 938. For each unmarked tuple in the new multiHeardLinks tuples (newMHL) 946, four cases are possible for the host of the newMHL. The host of the newMHL may be found in the curSHL 648, the curMHL 656, the curCL 664, or the curUOL 668. If the host is found in the

curSHL 648, then the system determines 650 whether there is a matching connector tuco between the newMHL and the curMHL. If there is a matching tuco, then the segment type of connection is changed 652. If there is not a matching tuco, then the host connection is moved 654 in the topology.

If the host is found in the curMHL tuples 656, then the system determines 658 whether there is a matching connector tuco in both the curMHL tuples and the newMHL tuples. If there is a matching connector tuco, then the host connection attribute is changed 660. If there is not a matching tuco, then the host connection is moved 662 in the topology. If the host is found in the curCL tuples 664, then the host is moved into a bus segment of a connector. If the host is found in the curUOL tuples 668, then the host connection is moved 670 in the topology.

Figure 20d shows another portion of the identify different tuples phase 938. For each unmarked tuple in the newCL tuples 672, there are three possibilities for the connector. The connector of the unmarked tuple in newCL can be found in the curSHL or curMHL 674, in the curCL 678, or in the curUOL 682. If each connector is found in the curSHL or curMHL list 674, then the system creates 676 a new point-to-point segment for the connectors. If the connectors are found in the curCL 678, then the connection attributes of the connectors are changed 680. If each connector is found in the curUOL tuples 682, then the host connection is moved 684 in the topology.

Another part of the identify different tuples phase 938 is shown in blocks 686 and 688 of Figure 20d. For each unmarked tuple in the newUOL tuples 686, the system checks 688 the timer/configuration to determine whether the host/conn should move into the default segment from its current segment.

An advantage of the system is that it may be schedulable. The system may map network topology continuously, as done by existing systems, or it may be scheduled to run only at certain intervals, as desired by the user. A further advantage of the system is that it is capable of processing multiple connections between the same devices and of processing connection meshes, because it tracks each nodal connection independently, without limitations on the types of connections that are permitted to exist.

1        Although the present invention has been described with respect to particular embodiments  
2        thereof, variations are possible. The present invention may be embodied in specific forms without  
3        departing from the essential spirit or attributes thereof. It is desired that the embodiments described  
4        herein be considered in all respects illustrative and not restrictive and that reference be made to the  
5        appended claims for determining the scope of the invention.

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